

EO/IR Payload Display



EO/IR Payload Display

- Function: Provide timely display of payload status data and payload controls in support of effective use of the payload in imagery collection
- Applicable CSCs:
 - EO/IR Imagery Viewer & Capture
 - EO/IR Payload Control
- CSCs are linked depending on role



Design Drivers

- Situational Awareness
- Object of Interest Recognition & Assessment
- Minimum imagery capture rate of once every 15 seconds
- Minimum translation/alteration of image data to preserve original for C4I systems



Design Approach

- Analyze roles determine functionality required
- Collect suggestions and comments from operators at demos and AWEs
- Layout a display design
- Implement and take to demos and AWEs



Implementation Approach

- Draw video overlays (via standard windowing API) into Parallax HW memory
 - Create overlays at the workstation avoid "burning" overlays into video
 - Overlays can be converted to CGM for NITF files - C4I user can view overlays as required
- Reformat data from Parallax HW only as much as required for NITF compatibility



Functional Breakout

- Broken into three functional areas
 - EO/IR video display
 - NITF capture
 - EO/IR Payload controls
- Functions can be presented in a single HCI window as required by a given role

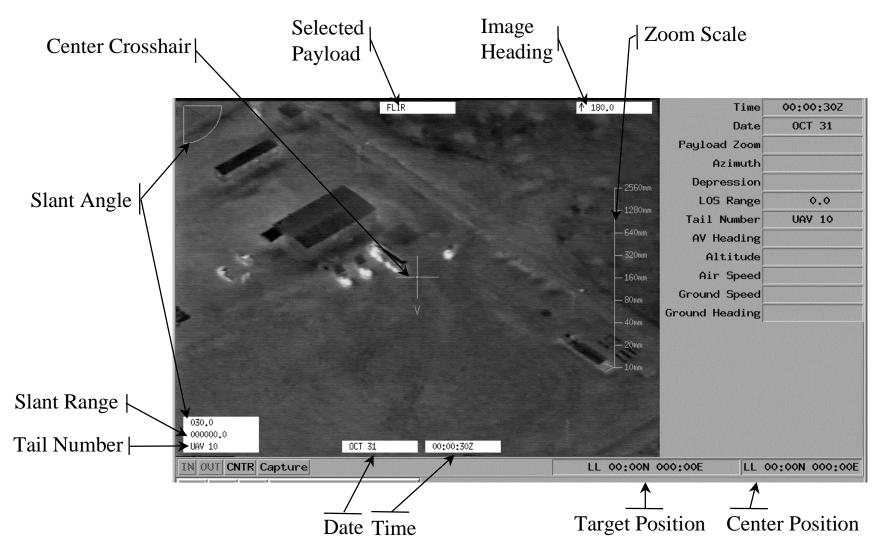


EO/IR Video Display

- Operator's view of what the payload is seeing
- Video is displayed at 30 frames per second
- Video overlayed with core status data
- Additional support status data displayed off of the video



EO/IR Video Display HCI





Data Flow (EO/IR Video)

AVSI/ Dat a Server Object

AV_EOIR_St at us

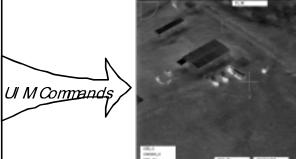
PL_ Depression_ Angle
PL_ Active_ Sensor
PL_ IR_ Polarity
PL_ Image_ Ang_ to_ North
PL_ Image_ Collection_ Time_ Week
PL_ Image_ Collection_ Time_ Second
PL_ Depression_ Angle
PL_ LOS_ Range_ to_ Target
PL_ Center_ Point_ Lat
PL_ Center_ Point_ Lon
PL_ Azimuth_ Angle
AV_ Tail_ Number

AV_Heading
AV_Altitude
AV_Airspeed_1
AV_Airspeed_2
AV_Airspeed_Sensor_Active
AV_ Ground_ Speed
AV_ Ground_ Track

AV Position Status

EO/IR Viewer SW

Computations (four corners) and data reformatting for HCI displays



Films 99 (1991) 302
State 6CF 36
Fingtoned Doom
Statement
Supervised Loop
LOOp Parent
LOOp Parent
LOOp Parent
Tail Manhor
Affiliach
Sir Spend
Sir Spend
Ground Speed
Ground Shooting



Operation (EO/IR Video)

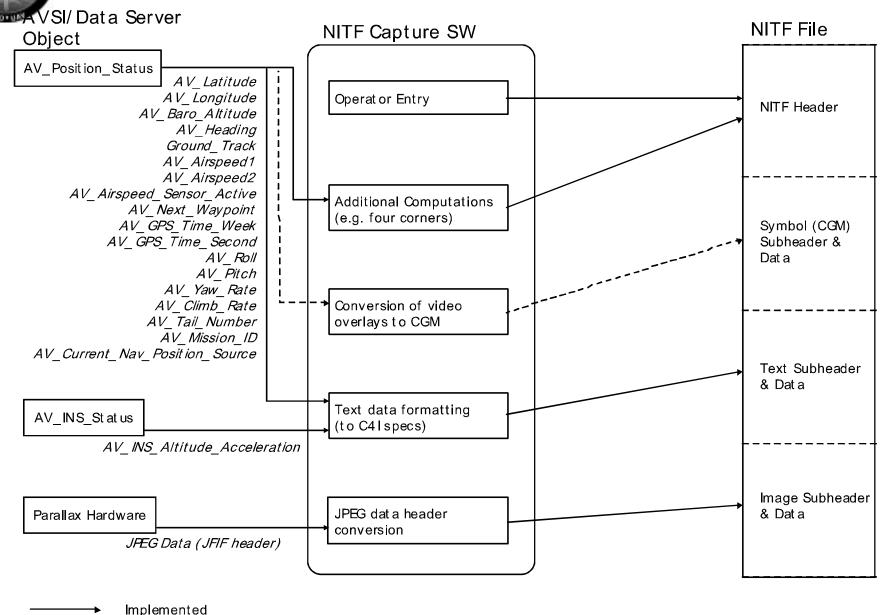
- Store status data as it arrives.
- Set internal flags that tell which AV/Payload status data items have changed since last update
- For each update of status data, determine what items changed and redraw the appropriate graphics.



NITF Capture

- One step operator process
- AV telemetry data embedded automatically
- NITF header information computed and embedded automatically

Data Flow (NITF Capture)



TCS PDR -- Part II



Operation (NITF Capture)

- Compute/format NITF header information (4 corners, date, etc)
- Capture image data from Parallax H/W
- Format JPEG header for NITF compliance
- Format AV telemetry as text data
- Format video overlays as CGM
- Create blank NITF file
- Insert header data, image, text, and CGM symbols into NITF file

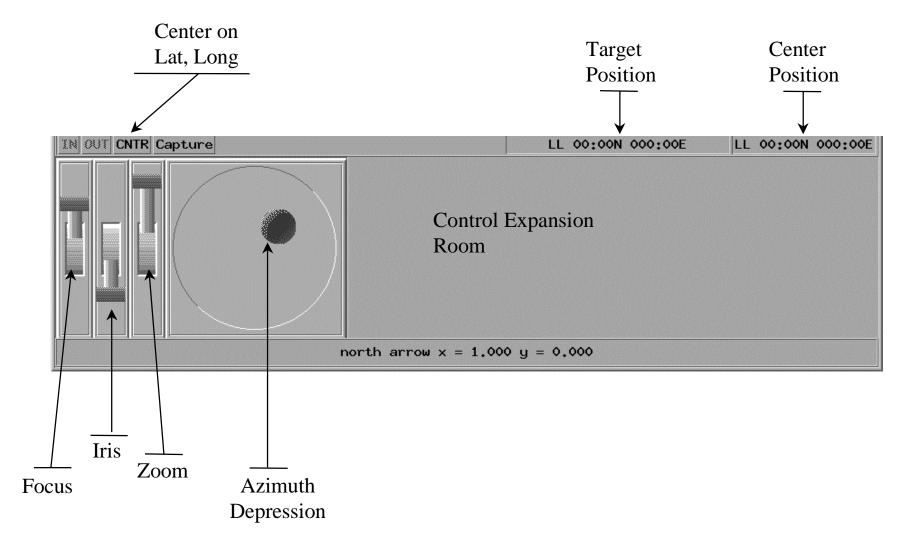


EO/IR Payload Controls

- Mix of graphical and textual based controls
 - standard GUI controls (buttons, text entry, etc)
 - graphical controls (joysticks, sliders)
 - operations on live video
- Used in conjunction with payload video display



EO/IR Payload Controls HCI





Data Flow (EO/IR Payload Controls)

AVSI/ Dat a Server Object

EOIR Command

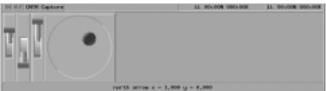
EO Power IR Power EOIR Payload Active EOIR Payload Pointing Mode EOIR Vertical Mode EOIR Point er Lat it ude EOIR Point er Longitude EOIR Pointer Altitude EOIR Depression EOIR Azimuth EOIR Depression Rate EOIR Azimuth Rate EO Payload Camera Select EO Payload Zoom EO Payload Focus EO Iris IR Payload Camera Select IR Payload Zoom IR Payload Focus IR Contrast IR Gain IR White Hot

EO/IR Control SW

Mapping from control inputs AVSI/DS object data items



TCS PDR -- Part II



IR Auto Gain Recalibrate



Operation (EO/IR Payload Controls)

- Receive events from window system as operator manipulates controls
 - For a continuous control, such as a slider,
 sample the state of the controls periodically,
 and format the appropriate Data Server objects
 - For a discrete control, such as a button,
 determine the state of the control and
 immediately format the appropriate DS objects
- Forward Data Server objects to AVSI



Combining Functionality for Different Roles

• CSC:

- Reads role from DS object
- Looks up required functionality for role
- Creates required DS and UIM objects

• UIM:

 Uses predetermined combination data to combine UIM objects into a single window



Combined Controls for MPO Role

